



## Wave Turbulence on the Surface of a Ferrofluid in a Magnetic Field

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We report the observation of wave turbulence on the surface of a ferrofluid mechanically forced and submitted to a static normal magnetic field. We show that magnetic surface waves arise only above a critical field. The power spectrum of their amplitudes displays a frequency-power law leading to the observation of a magnetic wave turbulence regime which is experimentally shown to involve a 4-wave interaction process. The existence of the regimes of gravity, magnetic and capillary wave turbulence is reported in the phase space parameters as well as a triple point of coexistence of these three regimes. Most of these features are understood using dimensional analysis or the dispersion relation of the ferrohydrodynamic surface waves.

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Wave turbulence is an out-of-equilibrium state where waves interact with each other nonlinearly through  $N$ -wave resonance process. The archetype of wave turbulence is the random state of ocean surface waves, but it appears in various systems: capillary waves [1,2], plasma waves in solar winds, atmospheric waves, optical waves, and elastic waves on thin plates [3]. Recent laboratory experiments of wave turbulence have shown new observations such as intermittency [4], fluctuations of the energy flux [5], and finite size effect of the system [2,6]. Some of these phenomena have recently been considered theoretically [7]. Wave turbulence theory allows us to analytically derive stationary solutions for the wave energy spectrum as a power law of frequency or wave number [3]. The spectrum exponent and the number  $N$  of resonant waves depend on both the wave dispersion relation and the dominant nonlinear interaction. Several theoretical questions are open, notably about the validity domain of the theory [8], and the possible existence of solutions for nondispersive systems [9]. In this context, finding an experimental system where the dispersion relation of the waves could be tuned by the operator should be of primary interest to test the wave turbulence theory.

A ferrofluid is a suspension of nanometric ferromagnetic particles diluted in a liquid displaying striking properties: the Rosensweig instability [10], the labyrinthine instability, magnetic levitation [11]. In contrast with usual liquids, the dispersion relation of surface waves on a ferrofluid displays a minimum which depends on the amplitude of the applied magnetic field [12,13]. Thus, one can easily tune the dispersion relation of surface wave from a dispersive to a nondispersive one with just one single control parameter. To our knowledge, no experimental observation of wave turbulence on a magnetic fluid has been reported. Here, we study the wave turbulence on the surface of a ferrofluid submitted to a normal magnetic field. We observe for the first time a regime of magnetic wave turbu-

lence. We characterize this regime by measuring the power spectrum and distribution of the magnetic wave amplitude.

The experimental setup is shown in Fig. 1. It consists of a cylindrical container, 12 cm in inner diameter and 4 cm in depth, filled with a ferrofluid up to a depth  $h = 2$  cm. The ferrofluid used is a ionic aqueous suspension synthesized with 8.5% by volume of maghemite particles ( $\text{Fe}_2\text{O}_3$ ;  $7.6 \pm 0.36$  nm in diameter) [14]. The properties of this magnetic fluid are: density,  $\rho = 1324$  kg/m<sup>3</sup>, surface tension,  $\gamma = 59 \times 10^{-3}$  N/m, initial magnetic susceptibility,  $\chi_i = 0.69$ , magnetic saturation  $M_{\text{sat}} = 16.9 \times 10^3$  A/m, and estimated dynamic viscosity  $1.2 \times 10^{-3}$  N s/m<sup>2</sup>. The container is placed between two horizontal coaxial coils, 25 cm (respectively 50 cm) in inner (respectively in outer) diameter, 7 cm far apart. A dc current is supplied to the coils in series by a power supply (50 V/35 A), the coils being cooled with water circulation. The vertical magnetic induction generated is 99% homogeneous in the horizontal plane [12], and is up to 780 G. It is measured by a Hall probe located in the center near the surface of the container. Surface waves are generated on the ferrofluid by the horizontal motion of a rectangular plunging Teflon wave maker driven by an electromagnetic vibration exciter. The wave maker is driven with low-frequency random vibrations (typically from 1 to 5 Hz). The amplitude of the surface waves  $\eta(t)$  at a given location is measured by a

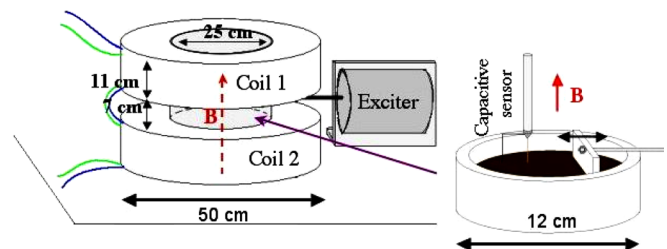


FIG. 1 (color online). Experimental setup.

capacitive wire gauge (plunging perpendicularly to the fluid at rest) with a 7.1 mm/V sensitivity [2].  $\eta(t)$  is recorded by means of an acquisition card with a 4 kHz sampling rate, low-pass filtered at 1 kHz during 300 s, leading to  $1.2 \times 10^6$  points recorded.

In the deep fluid approximation, the dispersion relation of linear inviscid surface waves on a magnetic fluid submitted to a magnetic induction  $B$  perpendicular to its surface, reads [11]

$$\omega^2 = gk - \frac{f[\chi]}{\rho\mu_0} B^2 k^2 + \frac{\gamma}{\rho} k^3, \quad (1)$$

where  $\omega$  is the wave pulsation,  $k$  its wave number,  $g = 9.81 \text{ m/s}^2$  the acceleration of the gravity,  $\mu_0 = 4\pi \times 10^{-7} \text{ H/m}$  the magnetic permeability of the vacuum, and  $f[\chi] \equiv \chi^2 / [(2 + \chi)(1 + \chi)]$ .  $\chi$  is the magnetic susceptibility of the ferrofluid which depends on the applied magnetic field  $H$  through Langevin's classical theory [15]

$$\chi(H) = \frac{M_{\text{sat}}}{H} \mathcal{L}\left(\frac{3\chi_i H}{M_{\text{sat}}}\right), \quad (2)$$

where  $\mathcal{L}(x) \equiv \coth(x) - 1/x$ , and thus on the magnetic induction,  $B$ , through an implicit equation since

$$B = \mu_0(1 + \chi)H. \quad (3)$$

For  $B = 0$ , the dispersion relation of Eq. (1) is monotonic, and is dominated by the gravity waves at small  $k$ , and by the capillary waves at large  $k$ . When  $B$  is increased, the quadratic term  $-B^2 k^2$  increases, and the dispersion relation becomes nonmonotonic: an inflection point appears at  $B = 0.93B_c$ , then a minimum which leads, at  $B = B_c$ , to the Rosensweig instability [11]. This stationary instability (a hexagonal pattern of peaks on the ferrofluid surface) occurs when  $\omega^2(k)$  becomes negative, that is for a critical induction  $B_c^2 = 2\mu_0\sqrt{\rho g \gamma} / f[\chi(H_c)]$  where  $\chi(H_c)$  is determined using Eqs. (2) and (3) [10]. This leads to the theoretical value of the critical induction  $B_c = 292.3 \text{ G}$  for the Rosensweig instability of our ferrofluid. When  $B$  is slowly increased, a direct visualization of the surface leads to an experimental value of  $B_c = 294 \pm 2 \text{ G}$  which is close to the above expected value.

The power spectrum of the wave amplitude on the surface of the ferrofluid is shown in Fig. 2 for different applied magnetic induction  $B$ . For  $B = 0$  (see the inset of Fig. 2), it displays similar results than those found with a usual fluid [2]: two power laws corresponding to the gravity and capillary wave turbulence regimes. The capillary regime is found to scale as  $f^{-2.9 \pm 0.1}$  in good agreement with the prediction of weak turbulence theory in  $f^{-17/6}$  [16], and the gravity regime is found in  $f^{-4.6}$ . The exponent of the gravity cascade being known to depend on the forcing parameter [2,6] (in contrast with the theoretical prediction  $\sim f^{-4}$  [17]), it is thus only fitted to measure the crossover frequency  $f_{\text{gc}}$  between gravity and capillary regimes. As previously reported with usual fluids [2],  $f_{\text{gc}}$  is also found here to decrease (from 26.6, 21 to  $17.2 \pm 0.3 \text{ Hz}$  for a random forcing of 1–6 Hz, 1–5 Hz, and 1–

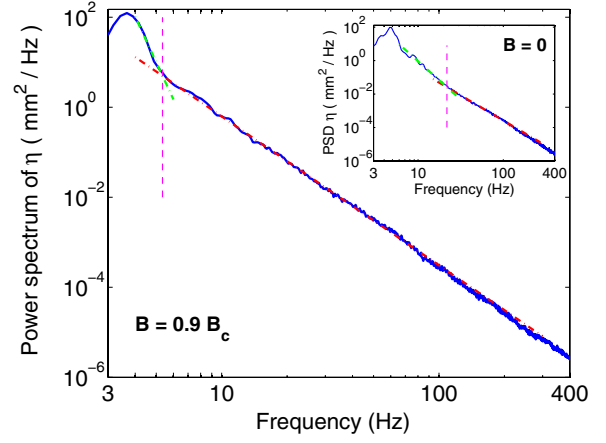


FIG. 2 (color online). Power spectrum of  $\eta(t)$  for two values of  $B$ . Inset:  $B = 0$ : Gravity and capillary wave turbulence regimes. Dashed lines have slopes  $-4.6$  and  $-2.9$ . Crossover:  $f_{\text{gc}} \approx 20 \text{ Hz}$ . Main:  $B = 0.9B_c$ : magnetocapillary wave turbulence. Dashed line has slope  $-3.3$ . Crossover:  $f_{\text{gc}} \approx 5 \text{ Hz}$ . Forcing parameters: 1–5 Hz.  $B_c = 294 \text{ G}$ .

4 Hz). The expected value is given by  $f_{\text{gc}} = \frac{1}{\pi} \sqrt{2g/l_c} \approx 15.2 \text{ Hz}$  where  $l_c = \sqrt{\gamma/(\rho g)}$  [2]. Consequently, in order to study the crossover frequency dependence with the magnetic induction  $B$ , one has to rescale it by its value at  $B = 0$  such as  $\tilde{f}(B) \equiv f_{\text{gc}}(0)f(B)/f(0)$  (see below).

For  $B \neq 0$ , the power spectrum of wave amplitudes shows two striking new results. As shown in Fig. 2, the crossover frequency is strongly decreased down to roughly 5 Hz, and a power law in  $f^{-3.3}$  appears in roughly all the accessible frequency range. Let us try first to understand this latter observation. The power spectrum of  $\eta(t)$  can be derived by dimensional analysis for the gravity and capillary wave turbulence regimes, respectively, as [9]  $S_{\eta}^{\text{grav}}(f) \sim \epsilon^{1/3} g f^{-4}$  and  $S_{\eta}^{\text{cap}}(f) \sim \epsilon^{1/2} (\frac{2}{\rho})^{1/6} f^{-17/6}$ , where  $\epsilon$  is the energy flux [dimension  $(L/T)^3$ ]. Since gravity wave turbulence is a 4-wave interaction process, and capillary waves a 3-wave one, it gives the dependence of the energy flux exponent in  $\epsilon^{1/(N-1)}$  for a  $N$ -wave process [9]. One can also derive dimensionally the power spectrum for the magnetic wave turbulence regime as

$$S_{\eta}^{\text{mag}}(f) \sim \epsilon^{\alpha} \left( \frac{B^2}{\rho\mu_0} \right)^{(2-3\alpha)/2} f^{-3}. \quad (4)$$

In contrast with the above dispersive systems, this  $-3$  frequency exponent does not depend on the energy flux exponent  $\alpha$ , that is on the number  $N$  of resonant waves. The frequency exponent predictions for the magnetic and capillary regimes, respectively  $-3$  and  $-17/6 \approx -2.8$  cannot be distinguished experimentally within our experimental accuracy. This could explain that only one single slope is observed on Fig. 2 which thus corresponds to a “magnetocapillary” wave turbulence regime.

Figure 3 shows the frequency exponent of the magnetocapillary spectrum when  $B$  is increased. For small  $B$ ,

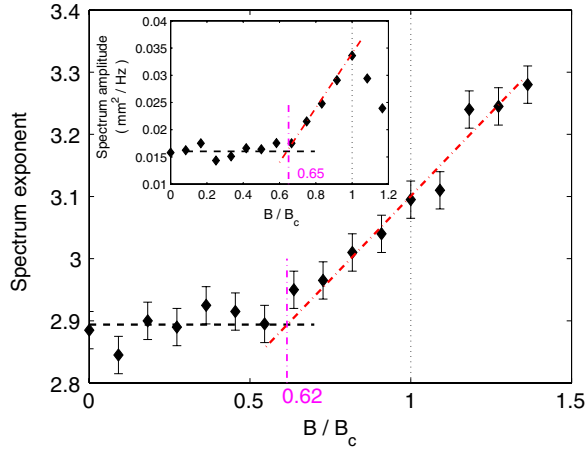


FIG. 3 (color online). Exponent of the magnetocapillary spectrum as a function of the dimensionless magnetic induction  $B/B_c$ . Inset: Amplitude of the power spectrum (averaged between 8 and 18 Hz) as a function of  $B/B_c$ . Forcing parameter:  $1 \leq f \leq 4$  Hz.  $B_c = 294$  G.

capillary waves are dominant and the exponent is found roughly constant  $\approx -2.9$  in good agreement with the capillary prediction. When  $B/B_c \geq 0.65$ , magnetic waves becomes dominant (see below), and the exponent begins to slightly increase with  $B$  up to  $-3.1$  in rough agreement with the  $-3$  prediction of Eq. (4). For  $B/B_c \geq 1$ , the Rosensweig instability occurs, and the spectrum exponent strongly changes with  $B$ . This could be attributed to the growing of the hexagonal pattern. The inset of Fig. 3 shows the power spectrum amplitude (averaged between 8 and 18 Hz) as a function of  $B$ . The spectrum amplitude is found roughly constant when  $B$  is increased till  $B/B_c \approx 0.65$ , onset of the magnetic waves. Above this value, the spectrum amplitude increases roughly linearly with  $B$  up to  $B/B_c = 1$  where the instability occurs. Using Eq. (4), one can thus deduce from this linear dependence that  $2 - 3\alpha = 1$ , and thus  $\alpha = \frac{1}{3}$ . This experimentally shows that the magnetic wave turbulence observed involves a 4-wave interaction process.

The crossover frequency between the gravity and magnetocapillary regimes decreases when  $B$  is increased (see Fig. 2). Figure 4 then shows the evolution of the rescaled crossover frequency  $\tilde{f}(B)$  (see above) as a function of  $B$  for 3 different frequency bandwidths of the random forcing. When  $B$  is increased,  $\tilde{f}$  is found to decrease with the same law whatever the forcing frequency. Beyond  $B = B_c$ ,  $\tilde{f}$  is roughly of the same order than the upper frequency of the forcing, and consequently cannot be measured anymore. However, when  $B > B_c$  and for the 1–6 Hz forcing, the power spectrum displays three power laws (not shown here) showing a magnetocapillary crossover. This new crossover frequency is reported in Fig. 4 with (○) symbols without rescaling. For lower frequency bandwidths of vibration, the slope breaking is too small to allow an accurate measurement of the transition between the magnetic and capillary regime.

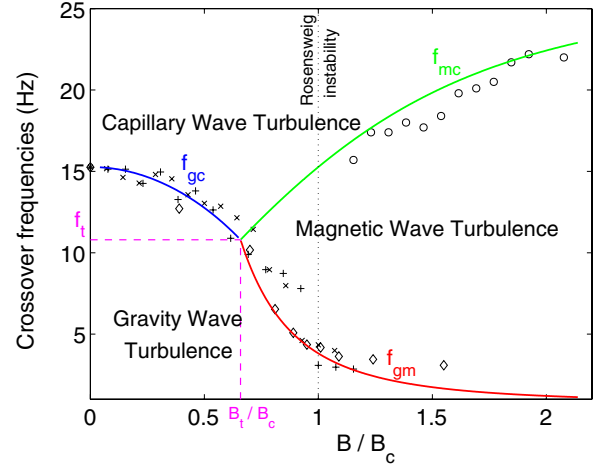


FIG. 4 (color online). Rescaled crossover frequencies,  $\tilde{f}(B) \equiv f_{gc}(0) \times f(B)/f(0)$  as a function of  $B$  for different frequency bandwidths of the random forcing: (×) 1 to 4 Hz, (◇) 1 to 5 Hz, and (+ or ○) 1 to 6 Hz. Theoretical curves  $f_{gc}$ ,  $f_{gm}$ , and  $f_{mc}$  are, respectively, from Eqs. (5)–(7). The triple point ( $f_t = 10.8$  Hz,  $B_t/B_c = 0.65$ ) is from Eq. (8).

The evolutions of these crossover frequencies with  $B$  are described as follows. Whatever  $B$ , Eq. (1) is dominated, at small  $k$ , by the linear term (gravity waves) and, at high  $k$ , by the cubic term (capillary waves). One can assume that the quadratic term (magnetic waves) dominates when it is greater than the linear and cubic terms. This arises when  $f[\chi]B^2 > \mu_0\sqrt{\rho g \gamma}$ , that is, using Eqs. (2) and (3) and the ferrofluid properties, when  $B > 0.65B_c$ . Thus, when  $B < 0.65B_c$ , no wavelength exists for which the magnetic term dominates in Eq. (1). When  $B > 0.65B_c$ , magnetic waves exist on a range of wavelength between the gravity and capillary ones. This explains why both the spectrum exponent and its amplitude shown in Fig. 3 change for  $B \approx 0.65B_c$ . Surprisingly, this critical magnetic induction has never been reported previously. The crossover frequencies are derived by balancing the dispersion relation terms each to each. For the gravity-capillary transition, one balances the first and the third terms of the second hand of Eq. (1), that is  $gk_{gc} = (\gamma/\rho)k_{gc}^3$ , thus for  $k_{gc} = \sqrt{\rho g/\gamma}$  which substituted into Eq. (1) gives

$$\omega_{gc}^2 = 2\sqrt{\frac{g^3\rho}{\gamma}} - \frac{gf[\chi]B^2}{\mu_0\gamma}, \quad \text{for } f[\chi]B^2 < \mu_0\sqrt{\rho g \gamma}. \quad (5)$$

Similarly, by balancing the first and second terms, the gravity-magnetic crossover frequency reads

$$\omega_{gm}^2 = \frac{\gamma}{\rho} \left[ \frac{\mu_0\rho g}{f[\chi]} \right]^3 B^{-6}, \quad \text{for } f[\chi]B^2 > \mu_0\sqrt{\rho g \gamma}. \quad (6)$$

Finally, by balancing the second and the third terms, the magnetocapillary crossover frequency reads

$$\omega_{mc}^2 = \frac{gf[\chi]}{\mu_0\gamma} B^2, \quad \text{for } f[\chi]B^2 > \mu_0\sqrt{\rho g\gamma}. \quad (7)$$

Using Eqs. (2) and (3) and the ferrofluid properties, these crossover frequency curves are plotted in Fig. 4 as a function of  $B/B_c$  and show a good agreement with the experimental data. This plot also shows the range of existence of magnetic waves for  $B/B_c > 0.65$  and of a triple point corresponding to the coexistence of the three domains (gravity, magnetic, and capillary ones). It can be derived by balancing the three terms of Eq. (1), which leads to

$$f_t = \frac{1}{2\pi} \left( \frac{g^3 \rho}{\gamma} \right)^{1/4} \quad \text{and} \quad B_t^2 = \mu_0 \sqrt{\rho g \gamma} / f[\chi(H_t)], \quad (8)$$

corresponding to  $f_t = 10.8$  Hz and  $B_t/B_c = 0.65$  in good agreement with the data of Fig. 4.

Finally, the probability density functions (PDFs) of the wave amplitudes are shown in Fig. 5 for different value of  $B/B_c$ , at high enough amplitude of forcing. For  $B = 0$ , the PDF is asymmetrical due to the strong steepness of the waves as for usual fluids [2]. This means that the deep troughs are rare, whereas high crests are much more probable, thus showing the nonlinear nature of the wave interactions in a wave turbulence regime. The PDF asymmetry is enhanced when  $B$  is increased. Note also that the most probable value of the PDF is more and more negative as  $B$  increases, although its mean value  $\langle \eta \rangle$  is zero as expected. The bottom inset of Fig. 5 shows that all these PDFs normalized to its standard deviation value,  $\sigma_\eta$ , roughly

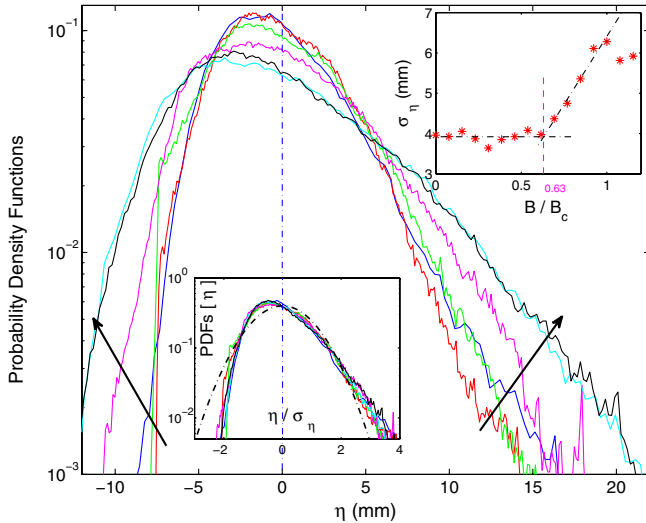


FIG. 5 (color online). Probability density functions of wave amplitude  $\eta$  for different values of the dimensionless magnetic induction, from  $B/B_c = 0, 0.3, 0.54, 0.77, 0.92$  to  $1.2$  (see the arrows). Forcing parameter:  $1 \leq f \leq 4$  Hz. Bottom inset: Same PDFs displayed using the reduced variable  $\eta/\sigma_\eta$ . Gaussian fit (dashed line). Top inset: Standard deviation of wave amplitude  $\sigma_\eta$  as a function of  $B/B_c$ .

collapse on a single non-Gaussian distribution. This means that the distribution depends only on  $\sigma_\eta$ . The top inset of Fig. 5 then shows the evolution of  $\sigma_\eta$  as a function of  $B/B_c$ . For  $B/B_c \leq 0.63$ , the rms value amplitude of the waves does not depend on the magnetic induction. Note that this value is very close to the above predicted onset of magnetic waves  $B_t/B_c = 0.65$ . When this onset is exceeded,  $\sigma_\eta$  increases roughly linearly with  $B$  up to the occurrence of the Rosensweig instability at  $B_c$ .

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